

Complex Variables Notes

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March 7, 2016

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1 Fundamentals and Techniques

1.1 Complex Numbers and Elementary Functions

1.1.1 Properties

We define an imaginary number as

$$i^2 = -1$$

While a complex number is defined as

$$z = x + iy$$

The common functions \Re and \Im yield the real and imaginary parts of a complex number respectively.¹ We can also express complex numbers in polar coordinates.

$$x = r \cos \theta$$

$$y = r \sin \theta$$

Using Euler's Identity,

$$\cos \theta + i \sin \theta = e^{i\theta}$$

the alternate form is defined as

$$z = x + iy = r (\cos \theta + i \sin \theta) = re^{i\theta}$$

$$r = \sqrt{x^2 + y^2} = |z|$$

$$\tan \theta = \frac{y}{x}$$

The complex conjugate is defined as

$$x - iy \equiv re^{-i\theta}$$

We can define some common equivalences.

- $\exp(2\pi i) = 1$
- $\exp(\pi i) = -1$
- $\exp\left(\frac{\pi i}{2}\right) = i$
- $\exp\left(\frac{3\pi i}{2}\right) = -i$
- $\exp(i\theta_1) \exp(i\theta_2) = \exp(i(\theta_1 + \theta_2))$
- $\exp(i\theta)^m = \exp(im\theta)$
- $\exp(i\theta)^{1/n} = \exp\left(\frac{i\theta}{n}\right)$

Another neat trick is to let $z = 1/t$ to analyze behavior at ∞ .

¹Also denoted as Re and Im

1.1.2 Stereographic Projection

We can visualize complex numbers with a stereographic projection. Zero is located at the North Pole, and infinity at the South Pole.

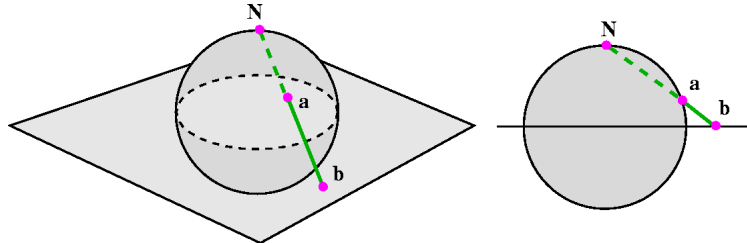


Figure 1: Stereographic Projection

These points are

$$X = \frac{4x}{|z|^2 + 4} \quad Y = \frac{4y}{|z|^2 + 4} \quad Z = \frac{2|z|^2}{|z|^2 + 4}$$

1.1.3 Elementary Functions

Similar to Real Analysis, we can define a neighborhood of some point z as the region enclosed by

$$|z - z_0| < \epsilon$$

As with sets, these can be closed, bounded, regions, domains, etc. . . .

We can also define functions of complex numbers, and as with real valued numbers, they mostly work the same. The simplest function is the power function.

$$f(z) = z^n$$

Which can be extended to define Polynomials and rational functions (as the result of dividing a polynomial function with another).

Limits also work the same, even with Radii of Convergence, etc.

Projections and Mappings work intuitively.

1.1.4 Example

Solve for all roots of the following equation: $z^4 + 2z = 0$.

$z(z^3 + 2) = 0$, so $z = 0$ or $z^3 = -2$, and then $r^3 = 2$, $e^{3i\theta} = e^{i\pi} \Rightarrow \theta = \pi/3 + 2\pi n/3$, $n = 0, 1, 2$. Thus, the roots are

$$z = 0, 2^{1/3}e^{i\pi/3}, 2^{1/3}e^{i\pi} = -2^{1/3}, 2^{1/3}e^{5i\pi/3}$$

1.1.5 Limits

Theorem 1 ($\epsilon - \delta$ Limit Definition). *A complex limit can be defined as*

$$\lim_{z \rightarrow z_0} f(z) = w_0$$

if for every sufficiently small $\epsilon > 0$, there is a $\delta > 0$ such that

$$|f(z) - w_0| < \epsilon \quad |z - z_0| < \delta$$

This is the traditional $\epsilon - \delta$ format that we're used to from real analysis.

Similarly, a function is said to be continuous if for all z ,

$$\lim_{z \rightarrow z_0} f(z) = z_0$$

The traditional definitions of Uniform and Absolute convergence also apply.

Using these limit definitions we can define the concept of a derivative.

$$f'(z_0) = \lim_{\Delta z \rightarrow 0} \left(\frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z} \right) = \lim_{z \rightarrow z_0} \left(\frac{f(z) - f(z_0)}{z - z_0} \right)$$

1.2 Analytic Functions and Integration

1.2.1 Analytic Functions

In order for a complex function to be differentiable, it has to satisfy the Cauchy-Riemann Conditions.

Theorem 2 (Cauchy-Riemann Conditions). *By writing the real and imaginary parts separately in the definition of a derivative, we get*

$$\begin{aligned} f(z) &= u(x, y) + iv(x, y) \\ f'(z) &= \lim_{\Delta x \rightarrow 0} \left(\frac{u(x + \Delta x, y) - u(x, y)}{\Delta x} + i \frac{v(x + \Delta x, y) - v(x, y)}{\Delta x} \right) \\ &= u_x(x, y) + iv_x(x, y) \end{aligned}$$

Yielding the Cauchy-Riemann conditions,

$$\begin{aligned} u_x &= v_y & v_x &= -u_y \\ u_r &= \frac{v_\theta}{r} & v_r &= -\frac{u_\theta}{r} \end{aligned}$$

Theorem 3. *The function $f(z) = u(x, y) + iv(x, y)$ is differentiable at a point $z = x + iy$ of a region in the complex plane if and only if the partial derivatives u_x , u_y , v_x , v_y , are continuous and satisfy the Cauchy-Riemann conditions at $z = x + iy$.*

For differentiability, we can use the term analyticity to mean the same thing, both for pointwise differentiability and differentiability over a region. Points that are not differentiable (analytic) are called singular points.²

Some properties follow.³

- Sums, Products, and Compositions of analytic functions are analytic.
- The reciprocal of an analytic function that is nowhere zero is analytic, as is the inverse of an invertible analytic function whose derivative is nowhere zero.

²Holomorphic is sometimes used as well (or instead) of analytic.

³https://en.wikipedia.org/wiki/Analytic_function#Properties_of_analytic_functions

An entire function is one that's analytic on the entire finite plane.

Taking the second derivative of the Cauchy-Riemann conditions yields Laplace's Equation.

$$\begin{aligned} u_{xx} = v_{xy} & & v_{yx} = -u_{yy} \\ \nabla^2 w = 0 \Rightarrow & \begin{cases} \nabla^2 u \equiv u_{xx} + u_{yy} = 0 \\ \nabla^2 v \equiv v_{xx} + v_{yy} = 0 \end{cases} \end{aligned}$$

A function that satisfies the concise Laplace Equation: $\nabla^2 w = 0$ is called a harmonic function in D . u and v are referred to as harmonic functions in D , and they are harmonic conjugates of each other.

1.2.2 Example

Let $f(z) = e^z = e^{x+iy} = e^x e^{iy} = e^x(\cos y + i \sin y)$. Verify Cauchy-Riemann for all x, y , and then show that $f'(z) = e^z$.

$$\begin{aligned} u &= e^x \cos y & v &= e^x \sin y \\ u_x &= e^x \cos y = v_y & & \\ v_y &= -e^x \sin y = -v_x & & \\ f'(z) &= u_x + iv_x = e^x(\cos y + i \sin y) = e^z & & \end{aligned}$$

1.2.3 Ideal Fluid Flow - Application of Laplace's Equation

Two dimensional ideal fluid flow is a great example of Laplace's Equation. This is fluid that is time independent, nonviscous, incompressible, and irrotational.

1. Incompressibility:

$$v_{1,x} + v_{2,y} = 0$$

Where v_1 and v_2 are the horizontal and vertical components.

2. Irrotationality:

$$v_{2,x} - v_{1,y} = 0$$

3. Simplified:

$$\begin{aligned} v_1 = \phi_x = \psi_y & & v_2 = \phi_y = -\psi_x \\ \mathbf{v} &= \nabla \phi \end{aligned}$$

ϕ is the velocity potential, and ψ the stream function. Cauchy-Riemann is satisfied for ϕ and ψ , therefore we have a complex velocity potential.

$$\begin{aligned} \Omega(z) &= \phi(x, y) + i\psi(x, y) \\ \Omega'(z) &= \phi_x + i\psi_x = \phi_x - i\psi_y = v_1 - v_2 \end{aligned}$$

1.2.4 Example

Uniform Flow is

$$\Omega(z) = v_0 e^{-i\theta_0} z = v_0 (\cos \theta_0 - i \sin \theta_0)(x + iy)$$

where v_0 and θ_0 are positive real constants. The corresponding velocity potential and velocity field is given by

$$\begin{aligned} \phi(x, y) &= v_0 (\cos(\theta_0 x) + \sin(\theta_0 y)) \\ v_1 = \phi_x &= v_0 \cos \theta_0 \quad v_2 = \phi_y = v_0 \sin \theta_0 \end{aligned}$$

which is identified with uniform flow making an angle θ_0 with the x axis. Alternatively, the stream function $\psi(x, y) = v_0 (\cos(\theta_0 y) - \sin(\theta_0 x)) = \text{const.}$ reveals the same flow field.

1.2.5 Multivalued Functions

A simple example of this is the square root function which takes on different values for n even or odd.

$$\begin{aligned} z &= w^2 & w &= \sqrt{z} \\ & & &= r^{1/2} e^{i\theta_p/2} e^{n\pi i} \end{aligned}$$

We can define these “points” where complex functions take on multiple values as branch points. In the same way that they’re referred to as branch points, branches of a multivalued function are when we restrict to only one set of continuous values. A branch cut is this restriction process.⁴

Log is more complicated, and we define it as such.

$$w = \log(z) = \log r + i\theta_p + 2n\pi i, \quad n = 0, \pm 1, \pm 2, \dots, \quad 0 \leq \theta_p < 2\pi$$

1.2.6 Example

Find the location of the branch points and discuss possible branch cuts for the following functions:

1. $(z - i)^{1/3}$

Let $z - i = \epsilon e^{i\theta_p}$ which is a circular contour centered at $z = i$. We have just a power function in terms of $\zeta = z - i$, so $z = i$ and $z = \infty$ are branch points. Any line connecting $z = \infty$ and $z = i$ is a branch cut, e.g. $\{z = iy | y \in [1, +\infty)\}$ is as good as any. There are 3 distinct branches.

2. $\log\left(\frac{1}{z-2}\right)$

$\log\left(\frac{1}{z-2}\right) = -\log(z-2)$. Again, this is $-\log(z)$ but with shifted origin. So the branch points are $z = 2$ and $z = \infty$. A branch cut must connect the branch points, it can be $\{z = x | x \in [2, +\infty)\}$ or $\{z = x | x \in (-\infty, 2]\}$.

⁴The real analogy here is a function like $\pm\sqrt{x}$, $x \in \mathbb{R}$. 0 is a branch point, and we often times just examine the branch where $\sqrt{x} > 0$. The analogous branch cut is $x > 0$.

1.2.7 Example

Solve for all values of z : $4 + 2e^{z+i} = 2$.

$$4 + 2e^{z+i} = 2 \Rightarrow e^{z+i} = -1 = e^{i\pi+2\pi in}, n \in \mathbb{Z}$$

Therefore

$$z + i = i\pi + 2\pi in \Rightarrow z = i(\pi - 1 + 2\pi n), n \in \mathbb{Z}$$

1.2.8 Example

Find the location of the branch points and discuss a branch cut structure associated with the function:

- $f(z) = \frac{z-1}{z}$

This is a rational function singular at $z = 0$, but single-valued, so no branch points.

- $f(z) = \log(z^2 - 3)$

Here $z^2 - 3$ is entire single-valued function so the only branch points are those where $z^2 - 3 = 0$ or $z^2 - 3 = \infty$. Thus, there are three branch points, $z = \pm\sqrt{3}$, and $z = \infty$. A branch cut must make sure there is no possibility going around and single of them, in this case it must connect all three points. E.g. consider a cut on real axis $\{z = x | x \in [-3, +\infty)\}$.

- $f(z) = \exp \sqrt{z^2 - 1}$

Since function e^z is entire (analytic on plane) the only possible branch points are those of $\sqrt{z^2 - 1}$, i.e. $z = \pm 1$ and $z = \infty$. However, doing the circle argument $z - 1 = r_1 e^{i\theta_1}$, $z + 1 = r_2 e^{i\theta_2}$, $\theta_1 \rightarrow \theta_1 + 2\pi$, $\theta_2 \rightarrow \theta_2 + 2\pi$, one sees that $z = \infty$ is not a branch point since $\exp(2\pi i + 2\pi i)/2 = 1$ which corresponds to encircling both $z = 1$ and $z = -1$, equivalent to encircling just $z = \infty$. Thus, $z = \infty$ is not a branch point even for $\sqrt{z^2 - 1}$. But $z = \pm 1$ are branch points, and a branch cut connecting them is $\{z = x | x \in [-1, 1]\}$.

1.2.9 More Complicated Multivalued Functions and Riemann Surfaces

If we have functions like the following

$$w = [(z - a)(z - b)]^{1/2}$$

We need to use a slightly more complicated branch cut/structure. We know that the points $z = a, b$ are both branch points (by letting $z = a + \epsilon_1 e^{i\theta_1}$ and as θ_1 varies from 0 to 2π , w jumps from $q^{1/2}$ to $-q^{1/2}$), and so we can define a branch cut as follows.

$$\begin{aligned} z - b &= r_1 e^{i\theta_1} \\ z - a &= r_2 e^{i\theta_2} \quad 0 \leq \theta_1, \theta_2 < 2\pi \end{aligned}$$

Our equation now becomes

$$w = (r_1 r_2)^{1/2} e^{i(\theta_1 + \theta_2)/2}$$

This process extends to more complicated functions, as for any w of the form

$$w = [(z - x_1)(z - x_2) \cdots (z - x_n)]^m$$

we can define our branch cuts to be

$$z - x_k = r_k e^{i\theta_k}$$

yielding

$$w = (r_1 r_2 \cdots r_n) e^{mi(\theta_1 + \theta_2 + \cdots + \theta_n)}$$

1.2.10 Example

Find the location of branch points and discuss a branch cut structure associated with the function:

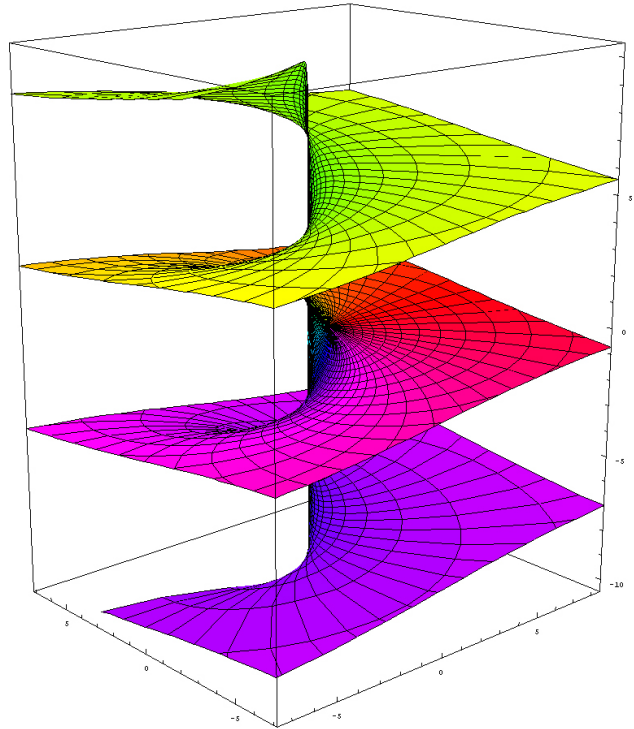
$$f(z) = \coth^{-1} \frac{z}{a} = \frac{1}{2} \log \left(\frac{z+a}{z-a} \right), a > 0$$

This is (up to a constant) log of rational function, so the branch points are those where $(z+a)/(z-a) = 0$ or ∞ , i.e. $z = \pm a$. As for $z = \infty$, it is not a branch point, as the limit equals 1, not zero. A cut must connect the two points, so a possible one is interval $[-a, a]$ on the real axis.

1.2.11 Riemann Surfaces

Instead of considering the normal complex plane with arbitrary “cuts”, it can be useful to instead consider a surface with multiple “sheets”. Any multivalued function only has one point that corresponds to each point on the sheet. This way, for any given sheet, the function is single-valued.

For the function $w^{1/2}$, since we have two branches, our Riemann surface is two-sheeted. For the log function, since it is infinitely multivalued, we have infinite sheets.

Figure 2: Riemann Surface for $\log(z)$

1.2.12 Complex Integration

Consider a function $f(t) = u(t) + iv(t)$. This function is integrable if u and v are integrable (with the same properties applying).

$$\int_a^b f(t) dt = \int_a^b u(t) dt + i \int_a^b v(t) dt$$

Defining a curve on the complex plane can be done parametrically, with form⁵

$$z(t) = x(t) + iy(t)$$

The path (contour) integral of function f on contour z is defined to be⁶

$$\int_C f(z) dz = \int_a^b f(z(t))z'(t) dt$$

This is really a line integral in the (x, y) plane.

⁵These curves are

- **Simple Curve** or **Jordan Arc** if it does not intersect itself.
- **Simple Closed Curve** or **Jordan Curve** if the endpoints meet.

⁶Contours are defined as piecewise smooth connected arcs. Simple closed is referred to as a Jordan Contour

Theorem 4. Suppose $F(z)$ is an analytic function and that $f(z) = F'(z)$ is continuous in a domain D . Then for a contour C lying in D with endpoints z_1 and z_2

$$\int_C f(z) dz = F(z_2) - F(z_1)$$

Since we can think of the parameterized complex plane as a vector field, for closed curves, we have

$$\oint_C f(z) dz = \oint_C F'(z) dz = 0$$

Note that everything here hinges on the analyticity of F and the continuity in domain D .

Theorem 5. Let $f(z)$ be continuous on a contour C . Then

$$\left| \int_C f(z) dz \right| \leq ML$$

where L is the length of C and M is an upper bound for $|f|$ on C .

Arc length can be defined (from Calc III) for a parameterized curve with form $z(t) = u(t) + iv(t)$ as

$$\int_a^b \sqrt{(u'(t))^2 + (v'(t))^2} dt$$

1.2.13 Example

Evaluate $\int_C \bar{z} dz$ for a contour from $z = 0$ to $z = 1$ to $z = 1 + i$.

$$\begin{aligned} \int_C \bar{z} dz &= \int_C (x - iy)(dx + i dy) \\ &= \int_{x=0}^1 x dx + \int_{y=0}^1 (1 - iy)(i dy) \\ &= \frac{1}{2} + i[y - iy^2/2]_0^1 \\ &= 1 + i \end{aligned}$$

1.2.14 Cauchy's Theorem

Theorem 6 (Cauchy). If a function f is analytic in a simply connected domain D , then along a simple closed contour C in D

$$\oint_C f(z) dz = 0$$

We also require that $f'(z)$ is also continuous in D .

“If $f(z)$ is analytic everywhere interior to and on a simple closed contour C , then $\oint_C f(z) dz = 0$.”

Again, NOTE that everything hinges on the fact that D must be simply connected. In order to use this, you need a simply connected domain D AND a simple closed contour C .

To best apply Cauchy's Theorem, we can use tricks like turning a complex contour into several simple contours, and deforming a simply connected domain so that the function is analytic on the domain.

1.2.15 Cauchy's Integral Formula, Its $\bar{\partial}$ Generalization and Consequences

Theorem 7. Let $f(z)$ be analytic interior to and on a simple closed contour C . Then at any interior point z

$$f(z) = \frac{1}{2\pi i} \oint_C \frac{f(\zeta)}{\zeta - z} d\zeta$$

This is referred to as Cauchy's Integral Formula.

Theorem 8. If $f(z)$ is analytic interior to and on a simple closed contour C then all the derivatives $f^{(k)}(z)$, $k = 1, 2, \dots$ exist in the domain D interior to C , and

$$f^{(k)}(z) = \frac{k!}{2\pi i} \oint_C \frac{f(\zeta)}{(\zeta - z)^{k+1}} d\zeta$$

Theorem 9. All partial derivatives of u and v are continuous at any point where $f = u + iv$ is analytic.

Theorem 10 (Liouville). If $f(z)$ is entire and bounded in the z plane (including infinity), then $f(z)$ is a constant.

Theorem 11 (Morera). If $f(z)$ is continuous in a domain D and if

$$\oint_C f(z) dz = 0$$

for every simple closed contour C lying in D , then $f(z)$ is analytic in D .

Theorem 12 (Maximum Principles). 1. If $f(z)$ is analytic in a domain D , then $|f(z)|$ cannot have a maximum in D unless $f(z)$ is a constant.

2. If $f(z)$ is analytic in a bounded region D and $|f(z)|$ is continuous in the closed region \bar{D} , then $|f(z)|$ assumes its maximum on the boundary of the region.

Theorem 13 (Generalized Cauchy Formula). If $\partial f / \partial \bar{\zeta}$ exists and is continuous in a region R bounded by a simple closed contour C , then at any interior point z

$$f(z) = \frac{1}{2\pi i} \oint_C \left(\frac{f(\zeta)}{\zeta - z} \right) d\zeta - \frac{1}{\pi} \iint_R \left(\frac{\partial f / \partial \bar{\zeta}}{\zeta - z} \right) dA(\zeta)$$

1.2.16 Theoretical Developments

Theorem 14 (Cauchy-Goursat). If a function $f(z)$ is analytic at all points interior to and on a simple closed contour, then

$$\oint_C f(z) dz = 0$$

1.3 Sequences, Series, and Singularities of Complex Functions

1.3.1 Definitions of Complex Sequences, Series, and Their Basic Properties

We can denote a sequence of functions that converge to some given function as

$$\lim_{n \rightarrow \infty} f_n(z) = f(z) \Leftrightarrow |f_n(z) - f(z)| < \epsilon$$

If the limit does not exist, or is infinite, the sequence is said to diverge for those values of z .

We say the sequence of functions converges uniformly if we can choose N on only ϵ , and not z . In other words, if for any z , the n^{th} function is ϵ close to $f(z)$.

Theorem 15. *Let the sequence of functions $f_n(z)$ be continuous for each integer n and let $f_n(z)$ converge to $f(z)$ uniformly in a region \mathcal{R} . Then $f(z)$ is continuous, and for any finite contour C inside \mathcal{R}*

$$\lim_{n \rightarrow \infty} \int_C f_n(z) dz = \int_C f(z) dz$$

Theorem 16 (Weierstrass M Test). *Let $|b_j(z)| \leq M_j$ in a region \mathcal{R} , with M_j constant. If $\sum_{j=1}^{\infty} M_j$ converges, then the series $S(z) = \sum_{j=1}^{\infty} b_j(z)$ converges uniformly in \mathcal{R} .*

Theorem 17 (Corollary: Ratio Test). *Suppose $|b_1(z)|$ is bounded, and*

$$\left| \frac{b_{j+1}(z)}{b_j(z)} \right| \leq M < 1, \quad j > 1$$

for M constant. Then the series

$$S(z) = \sum_{j=1}^{\infty} b_j(z)$$

is uniformly convergent.

1.3.2 Taylor Series

A power series about the point $z = z_0$ is defined as

$$f(z) = \sum_{j=0}^{\infty} b_j (z - z_0)^j$$

$$f(z + z_0) = \sum_{j=0}^{\infty} b_j z^j$$

With b_j, z_0 are constants. WLOG we can work with

$$f(z) = \sum_{j=0}^{\infty} b_j z^j$$

which is the $z_0 = 0$ case.

Theorem 18. *If the series*

$$f(z) = \sum_{j=0}^{\infty} b_j z^j$$

converges for some $z_ \neq 0$, then it converges for all z in $|z| < |z_*|$. Moreover, it converges uniformly in $|z| \leq R$ for $R < |z_*|$.*

Theorem 19 (Taylor Series). *Let $f(z)$ be analytic for $|z| \leq R$. Then*

$$f(z) = \sum_{j=0}^{\infty} b_j z^j$$

where

$$b_j = \frac{f^{(j)}(0)}{j!}$$

converges uniformly in $|z| \leq R_1 < R$.

The largest number R for which the power series converges inside the disk $|z| < R$ is called the radius of convergence.

Theorem 20. *Let $f(z)$ be analytic for $|z| \leq R$. Then the series obtained by differentiating the Taylor series termwise converges uniformly to $f'(z)$ in $|z| \leq R_1 < R$.*

Theorem 21. *If the power series converges for $|z| \leq R$, then it can be differentiated termwise to obtain a uniformly convergent series for $|z| \leq R_1 < R$.*

Theorem 22 (Comparison Test). *Let the series $\sum_{j=0}^{\infty} a_j z^j$ converge for $|z| < R$. If $|b_j| \leq |a_j|$ for $j \geq J$, then the series $\sum_{j=0}^{\infty} b_j z^j$ also converges for $|z| < R$.*

Theorem 23. *Let each of two functions $f(z)$ and $g(z)$ be analytic in a common domain D . If $f(z)$ and $g(z)$ coincide in some subportion $D' \subset D$ or on a curve Γ interior to D , then $f(z) = g(z)$ everywhere in D .*

Theorem 24. *Let D_1 and D_2 be two disjoint domains, whose boundaries share a common contour Γ . Let $f(z)$ be analytic in D_1 and continuous in $D_1 \cup \Gamma$ and $g(z)$ be analytic in D_2 and continuous in $D_2 \cup \Gamma$, and let $f(z) = g(z)$ on Γ . Then the function*

$$H(z) = \begin{cases} f(z) & z \in D_1 \\ f(z) = g(z) & z \in \Gamma \\ g(z) & z \in D_2 \end{cases}$$

is analytic in $D = D_1 \cup \Gamma \cup D_2$. We say that $g(z)$ is the analytic continuation of $f(z)$.

Theorem 25. *If $f(z)$ is analytic and not identically zero in some domain D containing $z = z_0$, then its zeroes are isolated; that is, there is a neighborhood about $z = z_0$, $f(z_0) = 0$, in which $f(z)$ is nonzero.*

1.3.3 Laurent Series

Theorem 26 (Laurent Series). *A function $f(z)$ analytic in an annulus $R_1 \leq |z - z_0| \leq R_2$ may be represented by the expansion*

$$f(z) = \sum_{n=-\infty}^{\infty} C_n (z - z_0)^n$$

in the region $R_1 < R_a \leq |z - z_0| \leq R_b < R_2$, where

$$C_n = \frac{1}{2\pi i} \oint_C \frac{f(z)}{(z - z_0)^{n+1}} dz$$

and C is any simple closed contour in the region of analyticity enclosing the inner boundary $|z - z_0| = R_1$.

Theorem 27. *The Laurent series defined above of a function $f(z)$ that is analytic in an annulus $R_1 \leq |z - z_0| \leq R_2$ converges uniformly to $f(z)$ for $\rho_1 \leq |z - z_0| \leq \rho_2$, where $R_1 < \rho_1$ and $R_2 > \rho_2$.*

Theorem 28. *Suppose $f(z)$ is represented by a uniformly convergent series*

$$f(z) = \sum_{n=-\infty}^{\infty} b_n (z - z_0)^n$$

in the annulus $R_1 \leq |z - z_0| \leq R_2$. Then $b_n = C_n$, with C_n previously defined.